# Block Coordinate Descent for Mesh Quality Improvement

## (Sachin Natesh)



(b) Optimized Mesh 2

An Exploration of Optimization on Smooth Manifolds

# (Brandon Finley, David Lujan)

Retraction  $R_x(v) = \frac{x+v}{\|x+v\|}$  on the sphere

# Bayesian Optimization: A Class of Zero-th Order Optimization Algorithms (Kevin Doherty, Killian Wood)







# Image Optimization (Jacob Spainhour, Damien Beecroft, Spas Angelov)





### (Nick Dietrich) Point Correlation [Lon,Lat] = [0.0] Hr 20, $\alpha = 7025.61$ km 60 20 -20 -40 -60 50 100 150 -150 -100 -50 Longitude [deg]

# Approximating the Natural Gradient





# An overview of sparse recovery with convex optimization

# (Mike Huffman, Steven Kordonowy)

**Theorem 1.** (Theorem 1.3 in [1]) Assume e is supported on a set S of size k. If  $\delta_k + \delta_{2k} + \delta_{3k} < 1$ , then e is the unique solution to  $(P_1)$ .

In order to prove Theorem 1, we prove the existence of a dual variable with helpful properties and then show that our solutions to  $(P_1)$  must be unique. We argue there exists a dual variable  $\nu$ that obeys

- 1.  $\langle \nu, v_j \rangle = sgn(e_j)$  for  $j \in S$
- 2.  $|\langle \nu, v_i \rangle| < 1$  for all  $j \notin S$

Lagrangian optimality conditions for  $(P_1)$  provides some intuition as to where these properties arise. The Lagrangian of  $(P_1)$  is given by  $\mathcal{L}(d,\nu) = ||d||_1 + \nu^T F(d-e)$ .  $\mathcal{L}$  is not differentiable at d = 0, so we focus on subgradients. In order to satisfy stationarity of the KKT conditions, we must

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Robust PCA of boats in the sea using APG

Approximate Hessian Based ARC for Deep Learning

## (Cooper Simpson, Jaden Wang)

![](_page_0_Figure_32.jpeg)

# **APPM 5630** "Advanced Convex Optimization" Prof. Becker, spring 2021

**Student projects** 

# Mirror Descent Learning in Continuous Games (Maneesha Papireddygari)

**Theorem 1.** For any  $\delta > 0$ ,  $\exists T(\delta)$ , such that for any  $t \ge T(\delta)$ , if  $x^t \in \widetilde{B}(x^*, \delta)$ , then  $x^{\widetilde{t}} \in \widetilde{B}(x^*, \delta)$ ,

True Functior

Samples

 $t_i^{t+1} = y_i^t + \alpha^t v_i(x^t)$ 

![](_page_0_Figure_37.jpeg)

Heat Transfer Optimization in 1D

(1)